

## **Tutorial Outline**

### ***Interactive Robot Learning***

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#### Abstract:

This tutorial focuses on the main methods and models enabling humans to teach social agents, and in particular social robots, using natural interaction. Humans guide the learning process of such agents by providing various teaching signals, which could take the form of instructions, advice, demonstrations or either feedback. The tutorial will introduce human teaching policies and strategies, which are currently studied through lenses ranging from low-level signals to Markov Decision Processes. We will particularly show how Bayesian models of human teaching are currently employed to account for the natural pedagogy of humans. This will include main concepts of social learning such as signaling and curriculum teaching. Adequate interactive learning approaches will be detailed such as learning from demonstrations and from evaluative feedback. We will then present research opportunities and challenges in interactive robot learning.

#### Details:

##### Part 1: Introduction

- Interactive Machine Learning vs. Machine Learning
- Human social learning
- Humans teaching robots

##### Part 2: Human Teaching Strategies

- Generative models
- Modeling human rationality and irrationality
- Ostensive communication and teaching

##### Part 3: Learning from humans

- Learning from evaluative feedback
- Learning from demonstrations
- Evaluation of interactive robot learning models

##### Part 4: Opportunities and challenges

- Learning and teaching
- Explainable Embodied Agents
- Autotelic agents

#### Readings:

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